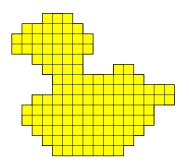
# Dynamic Minimum Length Polygon

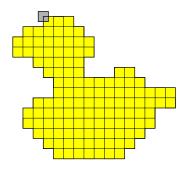
#### J.-O. Lachaud, X. Provençal

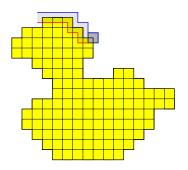


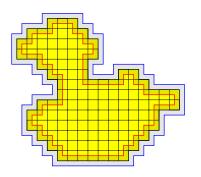


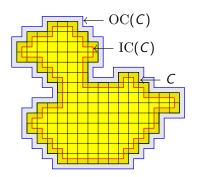
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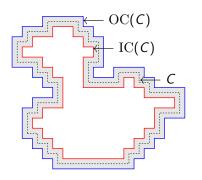






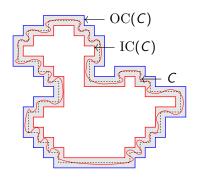
#### Definition

Given a digital contour C, its *inner* (resp. outer) contour IC(C) (resp. OC(C)) is the erosion (resp. dilatation) of the body of I(C) by the open unit square centrer on (0,0).



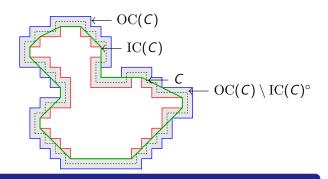
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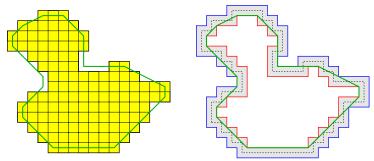


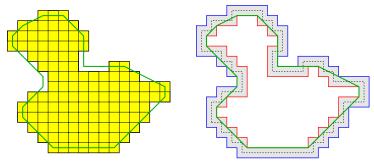
#### **Definition**

The minimum length polygon of C is a subset  $P \in \mathbb{R}^2$  such that,

$$P = \underset{A \in \mathcal{A}, IC(C) \subseteq A, \ \partial A \subset OC(C) \setminus IC(C)^{\circ}}{\operatorname{arg min}} \operatorname{Per}(A)$$

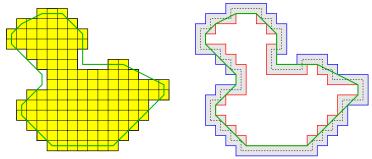
where A is the family of simply connected compact sets of  $\mathbb{R}^2$ .





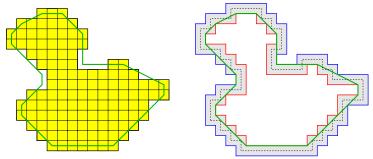
The MLP is a polygonal line whose vertices are centers of pixels along the inner or the outer contour, also :

• unique;



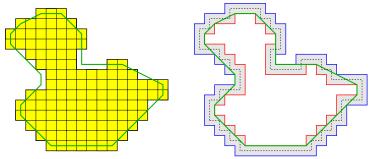
- unique;
- a good length estimator<sup>1</sup>;

<sup>&</sup>lt;sup>1</sup> Proved to be convergent on convex shapes.



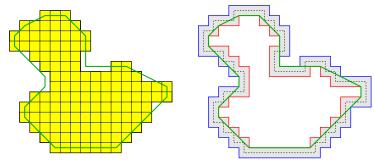
- unique;
- a good length estimator<sup>1</sup>;
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The MLP is a polygonal line whose vertices are centers of pixels along the inner or the outer contour, also :

- unique;
- a good length estimator<sup>1</sup>;
- a good tangent estimator;
- characteristic of the shape's convexity;
- reversible<sup>2</sup>.

<sup>2</sup> If aligned vertices are considered.

Proved to be convergent on convex shapes.

#### Computation of MLP

MLP is computable in time linear with respect of the length of C.

 J.-O. Lachaud, X. Provençal, Two linear-time algorithms for computing the minimum length polygon of a digital contour, Discrete Applied Mathematics (DAM), 2011.

### Segmentation using deformable models

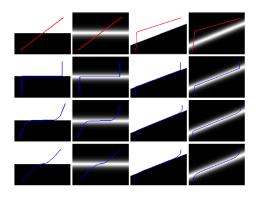
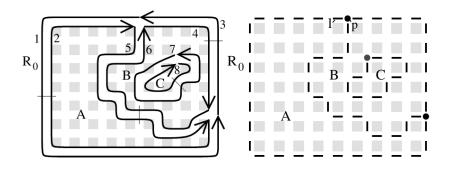


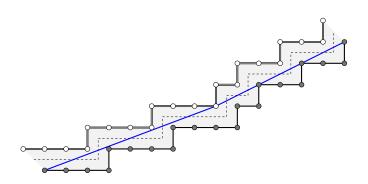
Fig. 4. Example of the minimization process using the Greedy1 algorithm. The gradient is computed with the Canny-Deriche method with scale coefficient 0.2. The input image represents a half-plane. (First row) Initialisation of the DDM. (Second row) Results of the minimisation process, the α coefficient used is equal to 0. (Third row) Results with α = 300. (Third row) Results with α = 300.

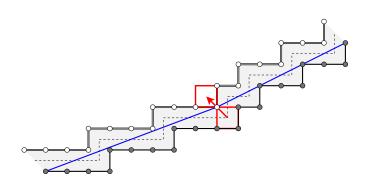
• F. de Vieilleville and J.-O. Lachaud, *Digital Deformable Model Simulating Active Contours*, in proc. DGCI2009, LNCS 5810, p.203-216, 2009.

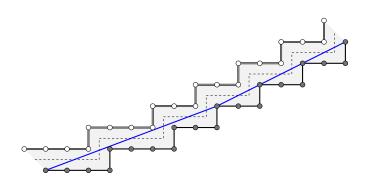
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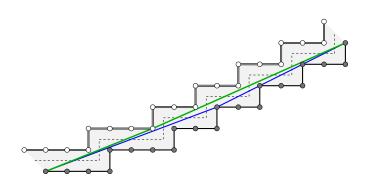


 G. Damiand, A. Dupas and J.-O. Lachaud, Combining Topological Maps, Multi-Label Simple Points, and Minimum-Length Polygons for Efficient Digital Partition Model, in proc. IWCIA2011, LNCS 6636, p. 208-221, 2011.









Goal : represent a digital contour C using a polygon whose versices are centers of pixels either on the inner contour IC(C) or on the outer contour OC(C).

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#### Definition

A grid-vector is a triplet  $x = ((p, q), k, \delta) \in \mathbb{N}^2 \times \mathbb{N} \times \mathbb{B}$ . where

- gcd(p,q) = 1, q/p is the *slope* of x (with  $1/0 = \infty$ ),
- $k \ge 1$  is its number of repetitions
- the boolean  $\delta$  indicates if x has one endpoint on the inner contour and one on the outer.

Notation : 
$$((p,q),k,\delta) = \begin{cases} (p,q)^k & \text{if } \delta \text{ is false,} \\ \widetilde{(p,q)^k} & \text{otherwise.} \end{cases}$$

Geometric interpretation of grid-vectors.

#### Definition

A context is an ordered pair of letters (a, b) among  $\{(0,1), (1,2), (2,3), (3,0), (0,3), (3,2), (2,1), (1,0)\}.$ 

Given a context (a, b), a grid-vectors defines the following vector as follow:

$$\frac{\stackrel{(a,b)}{(p,q)^k}}{\stackrel{(a,b)}{(p,q)^k}} = k(p\stackrel{\rightarrow}{a} + q\stackrel{\rightarrow}{b}), \qquad 1 \\
2 \stackrel{\stackrel{(a,b)}{\longleftrightarrow}}{\stackrel{(a,b)}{\longleftrightarrow}} \\
property \qquad 3$$

Geometric interpretation of grid-vectors.

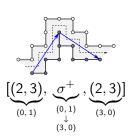
#### Definition

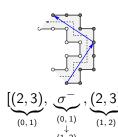
A context is an ordered pair of letters (a, b) among  $\{(0,1),(1,2),(2,3),(3,0),(0,3),(3,2),(2,1),(1,0)\}.$ 

Given a context (a, b), a grid-vectors defines the following vector as follow:

$$\frac{\stackrel{(a,b)}{(p,q)^k}}{\stackrel{(a,b)}{(p,q)^k}} = k(p\overrightarrow{a} + q\overrightarrow{b}), \qquad \qquad 1 \\
2 \leftrightarrow 0 \\
3 \\
(3,2)^1 \qquad (3,2)^1 \qquad (3,2)^1 \qquad (3,2)^1$$

- Operators :  $\sigma^+(a,b)=(\overline{b},a)$  : a turn toward the interior,  $\sigma^-(a,b)=(b,\overline{a})$  : a turn toward the exterior, with the convention  $\overline{0}=2,\overline{1}=3,\overline{2}=0,\overline{3}=1$ .
- Grid-curve :  $\Gamma = [I_0, I_1, \dots, I_{n-1}]$  where each  $I_i$  is either a grid-vector or one of the operators  $\sigma^-, \sigma^+$ .







#### Notations:

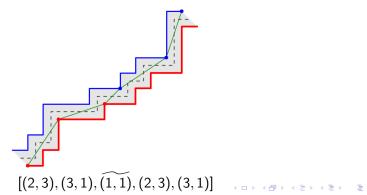
$$\bullet \stackrel{\stackrel{(a,b)}{\longrightarrow}}{\overrightarrow{\sigma^{-}}} = \stackrel{\stackrel{(a,b)}{\longrightarrow}}{\overrightarrow{\sigma^{+}}} = (0,0).$$

• Let 
$$x = ((p, q), k, \delta)$$
,  $x(a, b) = \begin{cases} (b, a) \text{ if } \delta \text{ is true,} \\ (a, b) \text{ otherwise.} \end{cases}$ 

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$$\sigma \stackrel{(a,b)}{\xrightarrow{\sigma^-}} = \stackrel{(a,b)}{\xrightarrow{\sigma^+}} = (0,0).$$

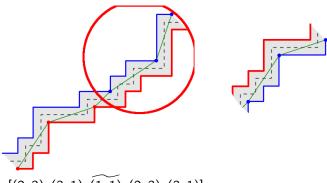
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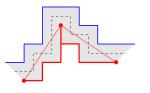
From grid-curves to polygons.

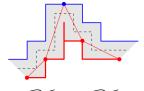
A grid-curve  $\Gamma = [I_0, I_1, \dots, I_{n-1}]$ , a context  $(a_0, b_0)$  and a start point  $P_0$  define a polygonal curve  $P_{\Gamma} = [P_0, P_1, \dots, P_n]$  in the following way :

$$P_{i+1} = P_i + \stackrel{(a_i,b_i)}{\stackrel{\longrightarrow}{\longrightarrow}}$$
 and  $(a_{i+1},b_{i+1}) = l_i(a_i,b_i).$ 

By fixing the first point on the inside or outside polygon, a discrete contour is defined unambiguously.

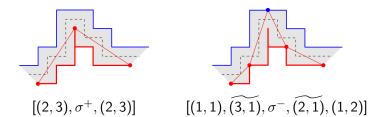
### Not unique





[(2,3), 
$$\sigma^+$$
, (2,3)] [(1,1),  $\widetilde{(3,1)}$ ,  $\sigma^-$ ,  $\widetilde{(2,1)}$ , (1,2)]

#### Not unique



#### Definition

Two grid-curves  $\Gamma$  and  $\Gamma'$  are *equivalent*, if they define the same digital contour and ends in the same orientation.

The MLP of the digital contour C is the shortest grid-curve in the equivalence class defined by C.

#### Relative orientation of grid-segements

#### Notation

Given 
$$x = ((p, q), k, \delta_x)$$
 and  $y = ((r, s), l, \delta_y)$ ,  $x \otimes y = \begin{cases} ps - qr & \text{if } \delta_y \text{ is false,} \\ pr - qs & \text{if } \delta_y \text{ is true.} \end{cases}$ 

Three cases							
$x \otimes y = 0$	$x \otimes y < 0$		$x \otimes y > 0$				
[(3,2),(3,2)]	[(2,3),(2,1)]	$[\widetilde{(1,3)},\widetilde{(2,3)}]$	[(3,1),(2,3)]	$[\widetilde{(3,2)},\widetilde{(2,1)}]$			

#### Relative orientation of grid-segements

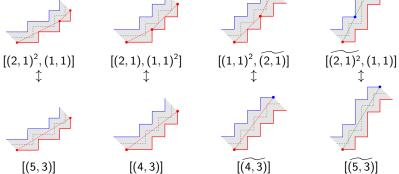
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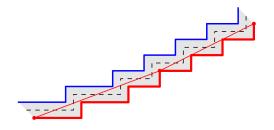
Three cases							
$x \otimes y = 0$	$x \otimes y < 0$		$x \otimes y > 0$				
$[(3,2)^2]$	[(2,3),(2,1)]	$[\widetilde{(1,3)},\widetilde{(2,3)}]$	[(3,1),(2,3)]	$[\widetilde{(3,2)},\widetilde{(2,1)}]$			

### Merge case : $x \otimes y = 1$

Let 
$$x = ((p,q),k,\delta_x)$$
 and  $y = ((r,s),l,\delta_y)$  with  $\delta_y = \text{false and min}(k,l) = 1$  or  $\delta_y = \text{true and } l = 1$  then 
$$[x,y] \equiv [z] \text{ where } z = \left\{ \begin{array}{l} ((kp+lr,kq+ls),1,\delta_x) & \text{if } \delta_y = \text{false.} \\ ((kp+ls,kq+lr),1,\neg\delta_x) & \text{otherwise.} \end{array} \right.$$

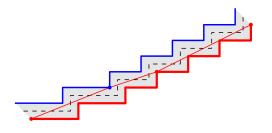


$$(8,3)\otimes(2,1)^3=2.$$



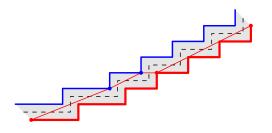
$$[(8,3),(2,1)^3]$$

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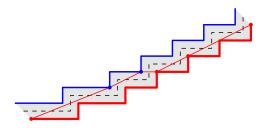
$$[(8,3),(2,1)^3] \equiv \widetilde{[(2,5),(3,1)},(2,1)^3]$$

$$(8,3)\otimes(2,1)^3=2.$$



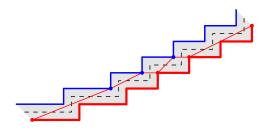
$$[(8,3),(2,1)^3] \equiv \widetilde{[(2,5)},(1,2),\widetilde{(1,0)},(2,1)^3]$$

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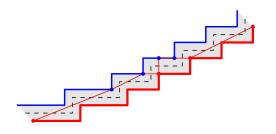
$$[(8,3),(2,1)^3] \equiv \widetilde{[(2,5)},(1,2),\widetilde{(1,0)},(2,1),(2,1)^2]$$

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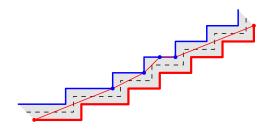
$$[(8,3),(2,1)^3] \ \equiv [\widetilde{(2,5)},(1,2),\widetilde{(1,0)},\widetilde{(1,1)},\widetilde{(1,0)},(2,1)^2]$$

$$(8,3)\otimes(2,1)^3=2.$$



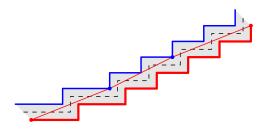
$$[(8,3),(2,1)^3] \ \equiv [\widetilde{(2,5)},(1,2),\widetilde{(1,0)},\widetilde{(1,0)},(0,1),\widetilde{(1,0)},(2,1)^2]$$

$$(8,3)\otimes(2,1)^3=2.$$



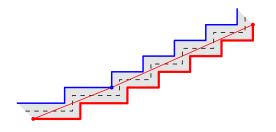
$$[(8,3),(2,1)^3] \equiv [\widetilde{(2,5)},(1,2),(1,1)(0,1),\widetilde{(5,2)}]$$

$$(8,3)\otimes(2,1)^3=2.$$



$$[(8,3),(2,1)^3] \ \equiv [\widetilde{(2,5)},(1,2)^2,\widetilde{(5,2)}]$$

$$(8,3)\otimes(2,1)^3=2.$$



$$[(8,3),(2,1)^3] \equiv [(2,5),(9,4)]$$

#### **Notation**

Let x = ((p, q), 1, false) and  $q/p = [u_0; u_1, \dots, u_n]$ .

- $q_i/p_i = [u_0; u_1, \dots, u_i],$   $x_{-1} = ((0,1), 1, \text{false}),$
- $x_i = ((p_i, q_i), 1, \text{false}), \quad \bullet \ x_{-2} = ((1, 0), 1, \text{false}).$

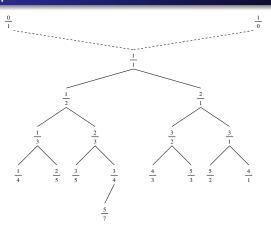
#### Definition

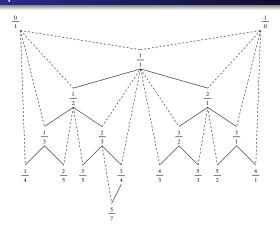
The basic splitting of the grid-vector  $x_n$  is the grid-curve :

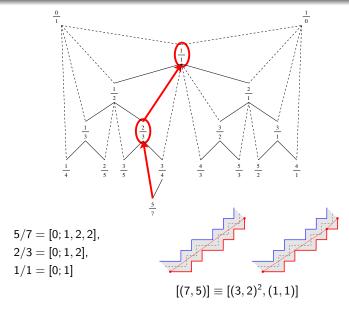
$$s(x_n) = \begin{cases} [x_{2m-2}, x_{2m-1}^{u_{2m}}] \text{ if } n = 2m, \\ [x_{2m}^{u_{2m+1}}, x_{2m-1}] \text{ if } n = 2m+1, \end{cases}$$

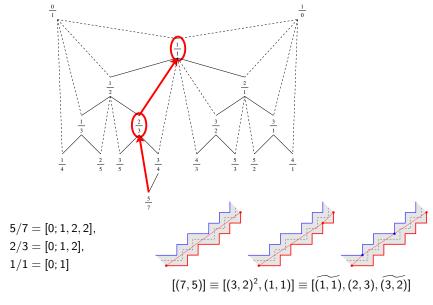
A grid-vector and it's basic splittings both define the same interpixel path.

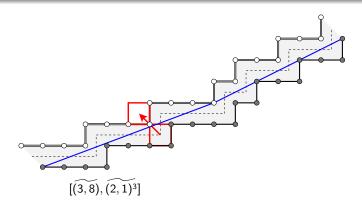
$$s(x) = [y, z] \implies y \otimes z = 1.$$

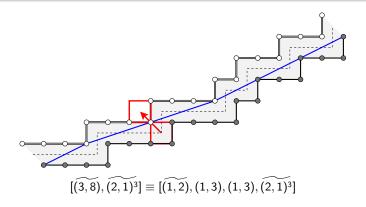




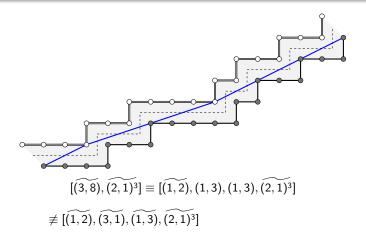




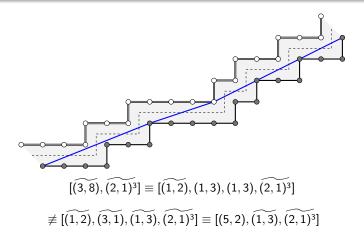




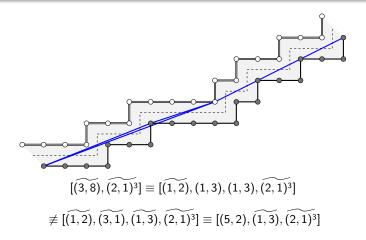
① Split grid-segments until one ends exactly on the pixel to flip. Let  $x = ((p,q),1,\delta_x)$  be the grid segment right before and  $y = ((r,s),1,\delta_y)$  be the grid-vector right after.



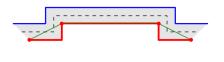
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- 2 Replace x by  $((q, p), 1, \neg \delta_x)$ .
- **3** Replace y by  $((r, s), 1, \neg \delta_y)$ .



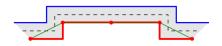
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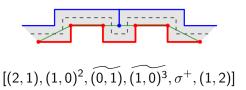
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- 2 Replace x by  $((q, p), 1, \neg \delta_x)$ .
- **3** Replace y by  $((r, s), 1, \neg \delta_v)$ .

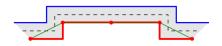


$$[(2,1),(1,0)^6,\sigma^+,(1,2)]$$

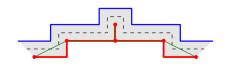


$$[(2,1),(1,0)^3,(1,0)^3,\sigma^+,(1,2)]$$

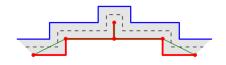




$$[(2,1),(1,0)^3,(1,0)^3,\sigma^+,(1,2)]$$

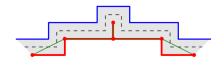


$$[(2,1),(1,0)^3,\quad \underbrace{\sigma^-,(1,0),\sigma^+,\sigma^+,(1,0),\sigma^-}_{\text{bumb}},\quad (1,0)^3,\sigma^+,(1,2)]$$



$$[(2,1),(1,0)^3,\quad \underbrace{\sigma^-,(1,0),\sigma^+,\sigma^+,(1,0),\sigma^-}_{\text{bumb}},\quad (1,0)^3,\sigma^+,(1,2)]$$

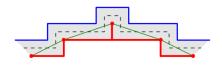
How to simplify  $\sigma^-$ ?



$$[(2,1),(1,0)^3,\quad \underbrace{\sigma^-,(1,0),\sigma^+,\sigma^+,(1,0),\sigma^-}_{\text{bumb}},\quad (1,0)^3,\sigma^+,(1,2)]$$

How to simplify  $\sigma^-$ ?

• Cancellation : 
$$[\sigma^-, \sigma^+] \equiv [\sigma^+, \sigma^-] \equiv [\,]$$



[
$$(2,1),(1,0)^3$$
,  $\underline{\sigma^-,(1,0),\sigma^+,\sigma^+,(1,0),\sigma^-}$ ,  $(1,0)^3,\sigma^+,(1,2)$ ]

How to simplify  $\sigma^-$ ?

- Cancellation :  $[\sigma^-, \sigma^+] \equiv [\sigma^+, \sigma^-] \equiv [\,]$
- Split the grid-edges in order to have a local part build only with  $\{\sigma^+,\sigma^-,(1,0),(0,1),\widetilde{(1,0)},\widetilde{(0,1)}\}$ . Operators  $\sigma^-$  are then simplify using local rules such as :

$$[(1,0),\sigma^-,(1,0),\sigma^+] \equiv [(1,1)] \text{ and } [\sigma^-,(1,0)^k,\sigma^+] \equiv [(0,1)^k]$$



#### Main result

#### **Proposition**

A grid-curve defining a digital contour may be simplified to a MLP using local rules.

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A grid-curve defining a digital contour may be simplified to a MLP using local rules.

#### Proposition

Given a grid-curve that is the MLP of a digital contour, this contour may be modified by adding or removing one pixel and its MLP updated in time sub-linear with respect to the length of the modified part of the MLP.

Implemente in project ImaGene available at
 gforge.liris.cnrs.fr/projects/imagene

C'est fini...

# MERCI!