

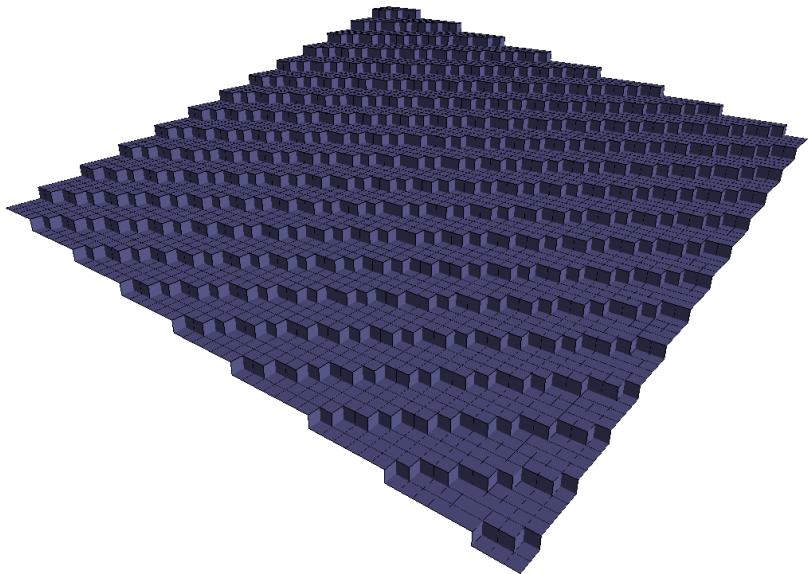
A study of Jacobi-Perron boundary words for the generation of discrete planes

Valérie Berthé, Annie Lacasse, Geneviève Paquin,
X. Provençal

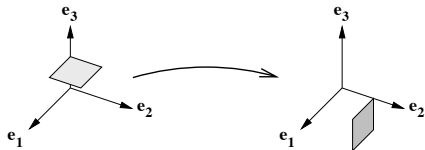
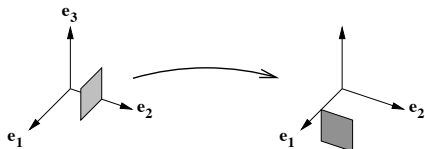
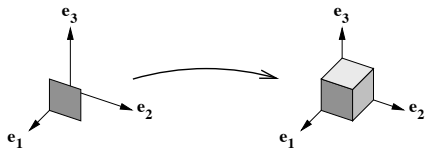


24 septembre 2010

Discrete plane



Generalized substitutions



Definition

The discrete line $\mathcal{L}(a, b, \mu, \omega)$ is defined by

$$\mathcal{L}(a, b, \mu, \omega) = \{(x, y) \in \mathbb{Z}^2 \mid 0 \leq ax + by + \mu < \omega\}.$$

- μ is the translation parameter of $\mathcal{L}(a, b, \mu, \omega)$.
- ω is the thickness of $\mathcal{L}(a, b, \mu, \omega)$.
- If $\omega = |a| + |b|$ then $\mathcal{L}(a, b, \mu, \omega)$ is said to be *standard*.

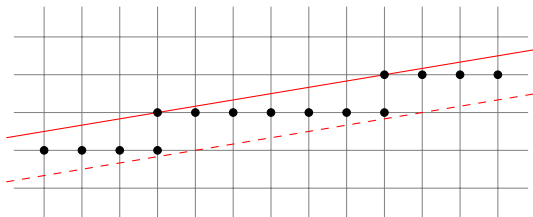
Reveillès 1991, Françon, Debled-Renesson, Kiselman, Vittone, Chassery, Gérard, Buzer, Brimkov, Barvena, Rosenfeld, Klette, ...

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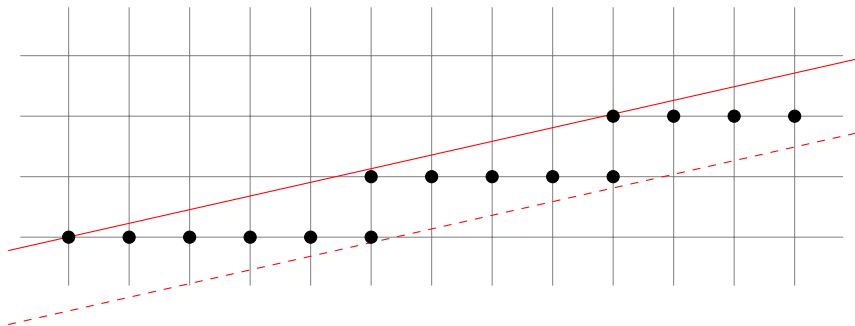
The discrete plane $\mathcal{P}(a, b, c, \mu, \omega)$ is defined by

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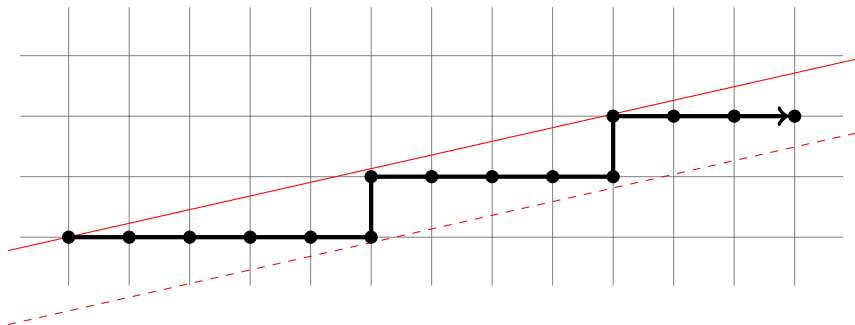
From discrete lines to words

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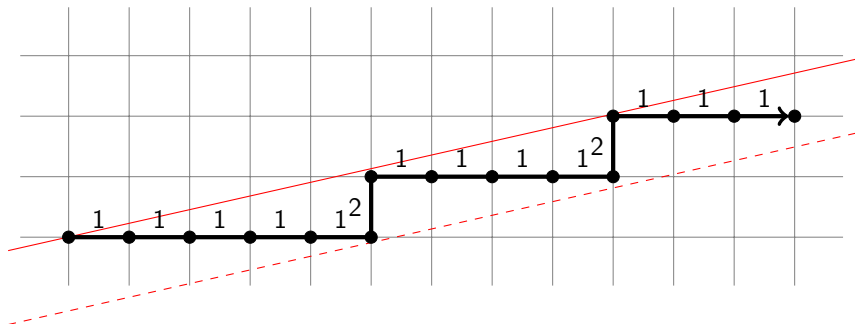
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$w = 11111211112111 \dots$

Definition (Morse and Hedlund 1940)

An infinite word w over a two-letter alphabet is *Sturmian* if, equivalently,

- w admits exactly $n + 1$ factors of length n ,
- w is balanced and aperiodic,
- w codes (as in the previous slide) a discrete line with irrational slope $\alpha = b/a > 0$.

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In the case where $\mu = 0$, then $w = 1 \cdot w'$ and w' is called a *characteristic* Sturmian word.

Generation of a characteristic Sturmian word

$$\alpha = [z_0; z_1, z_2, \dots] = z_0 + \frac{1}{z_1 + \frac{1}{z_2 + \frac{1}{z_3 + \dots}}}$$

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For each $n \geq 0$, let $s_n = \tau_{z_0} \circ \tau_{z_1} \circ \dots \circ \tau_{z_n}(2)$.

The characteristic Sturmian word w' of slope α is given by :

$$w' = \lim_{n \rightarrow \infty} s_n.$$

Euclid's algorithm

Computation of $[z_0; z_1, z_2, \dots]$ from $\alpha = b/a$.

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First steps :

$$u_2 = u_0 - \left\lfloor \frac{u_0}{u_1} \right\rfloor u_1,$$

$$u_3 = u_1 - \left\lfloor \frac{u_1}{u_2} \right\rfloor u_2,$$

\vdots

Euclid's algorithm, matrix form

Computation of $[z_0; z_1, z_2, \dots]$ from $\alpha = b/a = b_0/a_0$.

$$\begin{bmatrix} a_{n+1} \\ b_{n+1} \end{bmatrix} = \begin{bmatrix} -z_n & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} a_n \\ b_n \end{bmatrix} \quad \text{where } z_n = \left\lfloor \frac{b_n}{a_n} \right\rfloor$$

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If $a_n \neq 0$ let $M_n = \begin{bmatrix} 0 & 1 \\ 1 & z_n \end{bmatrix}$, otherwise $M_n = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$.

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$$\begin{bmatrix} a \\ b \end{bmatrix} = \lim_{n \rightarrow \infty} M_{z_1} M_{z_2} \cdots M_{z_n} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

In order to draw a discrete line of slope $\alpha = b/a$:

- Compute the matrices $M_{z_n} = \begin{bmatrix} 0 & 1 \\ 1 & z_n \end{bmatrix}$ in order to obtain the list $[z_0; z_1, z_2, \dots]$.
- Compute the prefixes characteristic Sturmian word w_α using the morphisms

$$\tau_{z_n} = \begin{cases} 1 \mapsto 2 \\ 2 \mapsto 2^{z_n}1 \end{cases}$$

- Draw the geometric representation of w_α .

Formalization of the Freeman chain-code

Let $\mathcal{A}_d = \{1, 2, \dots, d\}$ and (e_1, e_2, \dots, e_d) be the canonical base of \mathbb{R}^d . We consider \mathfrak{F} be the vector space of mappings from $\mathbb{Z}^d \times \mathcal{A}_d$ to \mathbb{R} that takes everywhere zero value except for a finite set.

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Let (\vec{x}, e_i) be the element of \mathfrak{F} that takes value 1 at (\vec{x}, i) and 0 elsewhere.

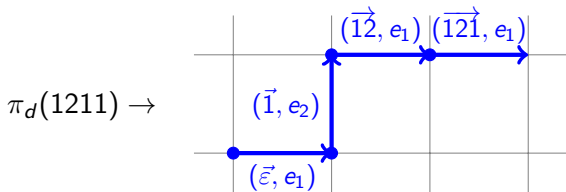
$$\begin{aligned} \pi_d : \mathcal{A}_d^* &\longrightarrow \mathfrak{F} \\ \pi_d(w) &= \sum_{w=p \cdot i \cdot s} (\vec{p}, e_i) \end{aligned}$$

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The E_1 operator

The *1-dimensional geometric realization* $E_1(\sigma)$ of a word morphism σ is the linear mapping defined on \mathfrak{F} such that :

$$\begin{array}{ccc} \mathcal{A}_d^* & \xrightarrow{\sigma} & \mathcal{A}_d^* \\ \downarrow \pi_d & & \downarrow \pi_d \\ \mathfrak{F} & \xrightarrow{E_1(\sigma)} & \mathfrak{F} \end{array}$$

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$$E_1(\sigma)(\vec{x}, e_i) := \sum_{\substack{uj \text{ prefix of } \sigma(i) \\ u \in \mathcal{A}_d^*, j \in \mathcal{A}_d}} (M_\sigma \vec{x} + \vec{u}, e_j).$$

The E_1^* operator

We consider \mathfrak{F}^* the dual space of \mathfrak{F} and the linear form :

$$(\vec{x}, e_i^*)(\vec{y}, e_j) \stackrel{\text{not.}}{=} \langle (\vec{y}, e_j), (\vec{x}, e_i^*) \rangle \stackrel{\text{def.}}{=} \begin{cases} 1 & \text{if } \vec{x} = \vec{y} \text{ and } i = j, \\ 0 & \text{otherwise.} \end{cases}$$

The dual operator E_1^* of E_1 is given by

$$\langle E_1(\sigma)(\vec{y}, e_j), (\vec{x}, e_i^*) \rangle = \langle (\vec{y}, e_j), E_1^*(\sigma)(\vec{x}, e_i^*) \rangle.$$

In the case where M_σ is unimodular

$$E_1^*(\sigma)(\vec{x}, e_i^*) := \sum_{j \in \mathcal{A}} \sum_{ui \text{ prefix of } \sigma(j)} (M_\sigma^{-1}(\vec{x} - \vec{u}), e_j^*).$$

Geometrical representation of \mathfrak{F}^*

We represent an element (\vec{x}, e_i^*) as :

$$(\vec{x}, e_i^*) \longrightarrow \left\{ \vec{x} + e_i + \sum_{i \neq j} \lambda_j e_j \mid \lambda_j \in [0, 1] \right\}.$$

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Examples :

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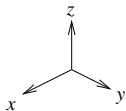


(\vec{x}, e_1^*)



(\vec{y}, e_2^*)

- $d = 3$



$(\vec{0}, e_1^*)$



$(\vec{0}, e_2^*)$



$(\vec{0}, e_3^*)$

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Given σ and τ two primitive substitutions :

$$E_1(\sigma) \circ E_1(\tau) = E_1(\sigma \circ \tau),$$

$$E_1^*(\sigma) \circ E_1^*(\tau) = E_1^*(\tau \circ \sigma).$$

Example in dimension 2

Given some slope $\alpha = b/a = [z_0; z_1, z_2, \dots]$ let's take a look at the geometric representations

- $E_1(\tau_{z_0}) \circ E_1(\tau_{z_1}) \circ \dots \circ E_1(\tau_{z_n})(\vec{0}, e_2),$

and

- $E_1^*(\tau_{z_0}) \circ E_1^*(\tau_{z_1}) \circ \dots \circ E_1^*(\tau_{z_n})(\vec{0}, e_2),$

for $n = 1, 2, \dots$

Recall that :

$$\begin{bmatrix} q_n \\ p_n \end{bmatrix} = M_{z_1} M_{z_2} \dots M_{z_n} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

and

$$\frac{p_n}{q_n} = [z_0; z_1, z_2, \dots, z_n]$$

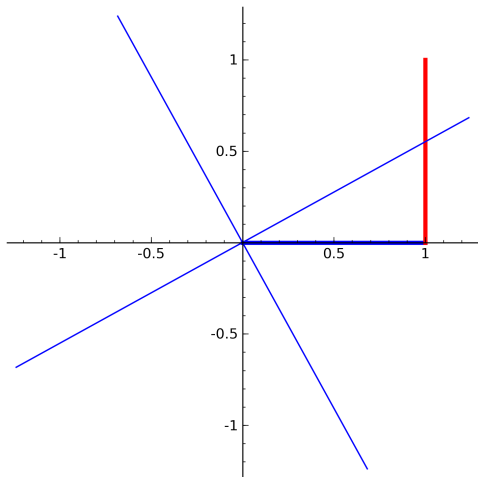
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$$(a, b) = (\pi, \sqrt{3}), \sqrt{3}/\pi = [0; 1, 1, 4, 2, 1, 2, 3, \dots],$$

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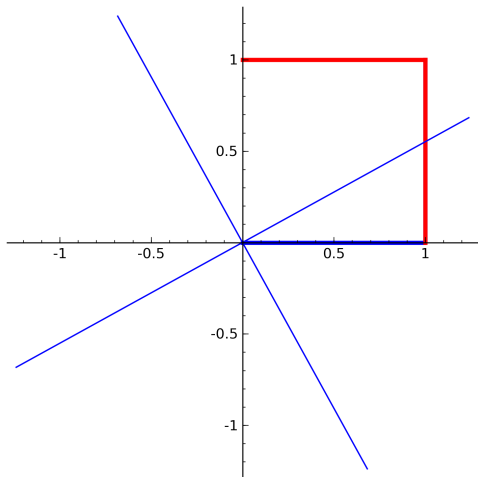
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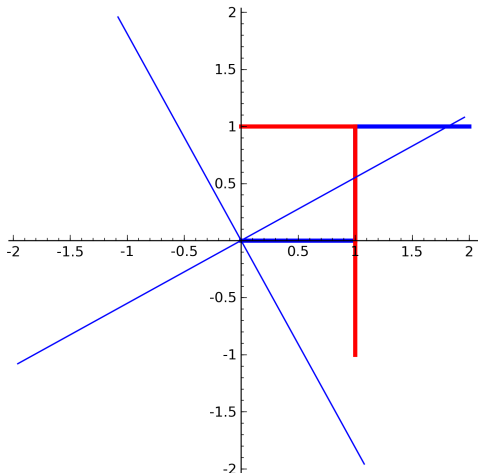
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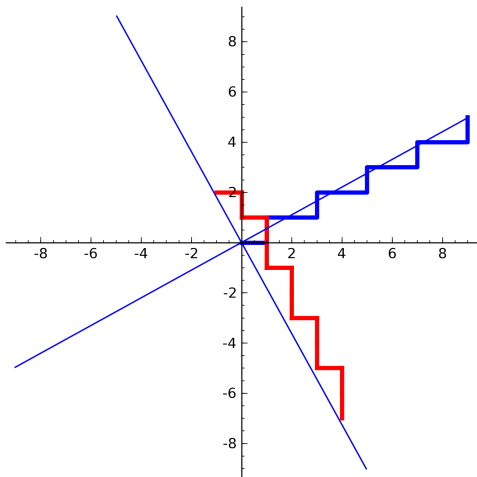
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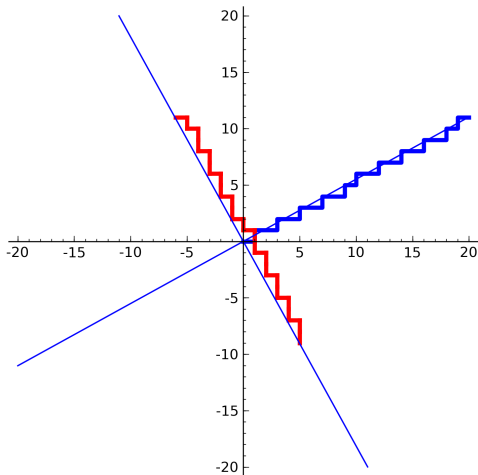
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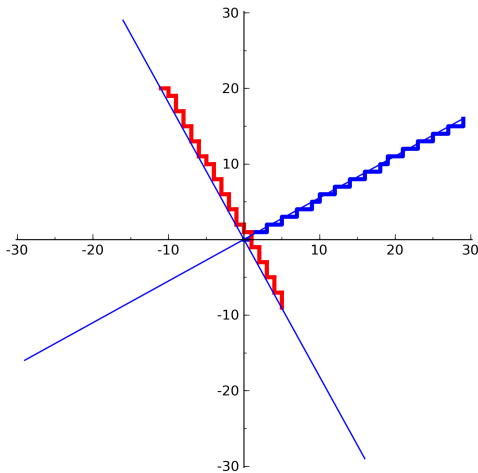
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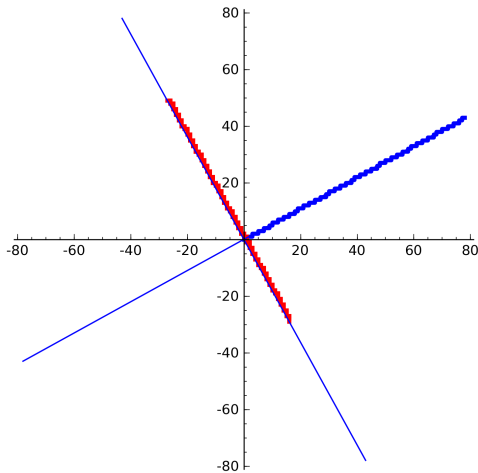
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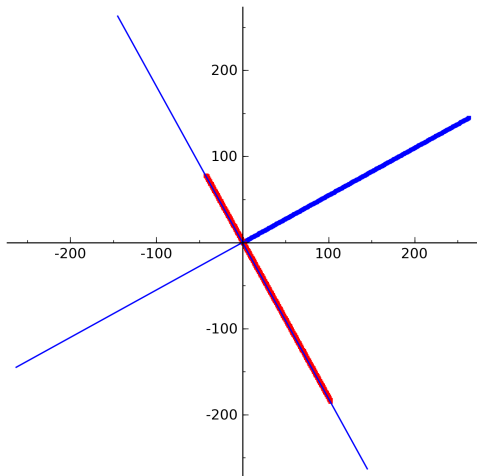


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Let $\mathcal{P}_{\vec{\alpha}}$ be the *plane* that passes through the origin with normal vector $\vec{\alpha}$.

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The primitive and unimodular case

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Proposition (Arnoux, Ito)

If σ is a primitive unimodular substitution, then

$$E_1^*(\sigma)(\mathfrak{G}_{\vec{\alpha}}) = \mathfrak{G}_{t_{M_\sigma}\vec{\alpha}}$$

Moreover, two distinct elements $(\vec{x}, e_i^*), (\vec{y}, e_j^*) \in \mathfrak{G}_{\vec{\alpha}}$ have disjoint images by $E_1^*(\sigma)$.

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- **Our contribution !**

Continued fraction

- *Best approximation* Let $\alpha = [z_0; z_1, \dots]$. For each $n \geq 0$, let $\frac{p_n}{q_n} = [z_0; z_1, z_2, \dots, z_n]$ then any $p, q \in \mathbb{N}$ such that $1 \leq q \leq q_n$ and $\frac{p}{q} \neq \frac{p_n}{q_n}$ satisfies

$$|q_n \alpha - p_n| < |q \alpha - p|.$$

See, e.g., Khintchine, Cassels.

Many possible generalizations : Jacobi-Perron, Brun, Poincaré, Selmer, ...

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Many possible generalizations : **Jacobi-Perron**, Brun, Poincaré, Selmer, ...

- Let $\alpha, \beta \in \mathbb{R}$ the Jacobi-Perron algorithm computes $(p_i, q_i, r_i)_{i \geq 1}$ such that for all $n \geq 0$,

$$\left| \alpha - \frac{p_n}{r_n} \right| < \frac{1}{r_n^{1+\delta}} \quad \text{and} \quad \left| \alpha - \frac{q_n}{r_n} \right| < \frac{1}{r_n^{1+\delta}}.$$

Jacobi-Perron's algorithm

- Input : $(a, b, c) \in \mathbb{R}^3$, $0 \leq \min(a, b)$, $\max(a, b) \leq c$

Initialization : $(a_0, b_0, c_0) := (a, b, c)$,

$$(a_{n+1}, b_{n+1}, c_{n+1}) := \begin{cases} \left(b_n - a_n \left\lfloor \frac{b_n}{a_n} \right\rfloor, c_n - a_n \left\lfloor \frac{c_n}{a_n} \right\rfloor, a_n \right) & \text{if } a_n \neq 0, \\ \left(0, c_n - b_n \left\lfloor \frac{c_n}{b_n} \right\rfloor, b_n \right) & \text{if } a_n = 0 \text{ and } b_n \neq 0, \\ (0, 0, c_n) & \text{if } a_n = b_n = 0. \end{cases}$$

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The *Jacobi-Perron matrices* are the unimodular matrices that satisfy :

$$\begin{bmatrix} a_n \\ b_n \\ c_n \end{bmatrix} = {}^t M_n \begin{bmatrix} a_{n+1} \\ b_{n+1} \\ c_{n+1} \end{bmatrix}$$

Jacobi-Perron matrices

- $(a_{n+1}, b_{n+1}, c_{n+1}) := (b_n - a_n B_n, c_n - a_n C_n, a_n)$

$$M_{B_n, C_n} := \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & B_n & C_n \end{bmatrix} \text{ with } B_n = \left\lfloor \frac{b_n}{a_n} \right\rfloor \text{ and } C_n = \left\lfloor \frac{c_n}{a_n} \right\rfloor,$$

- $(a_{n+1}, b_{n+1}, c_{n+1}) := (0, c_n - b_n E_n, b_n)$,

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- $(a_{n+1}, b_{n+1}, c_{n+1}) := (0, 0, c_n)$, $M_{\text{Id}} := \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

Jacobi-Perron substitutions

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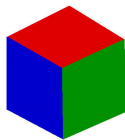
Notation : we note $(M_{\langle i \rangle})_{i \geq 1}$ (resp. $(\sigma_{\langle i \rangle})_{i \geq 1}$) the sequence of matrices (resp. substitutions) produced by the Jacobi-Perron algorithm.

Examples in dimension 3

Starting with the unit cube $\mathcal{U} = (\vec{0}, e_1^*), (\vec{0}, e_2^*), (\vec{0}, e_3^*)$.

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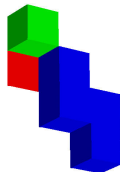


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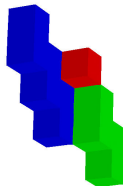


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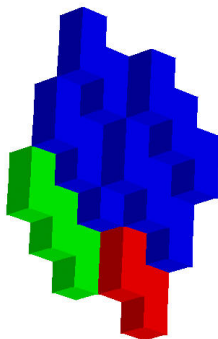


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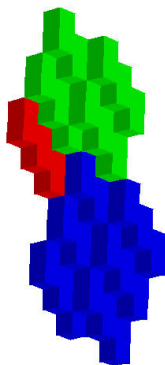


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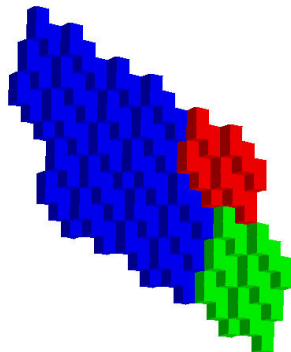


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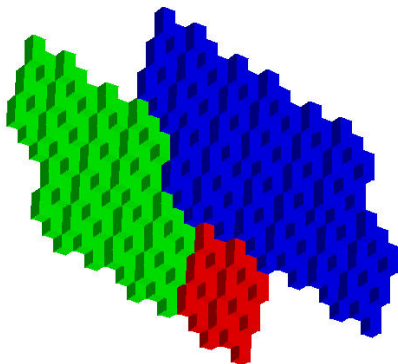


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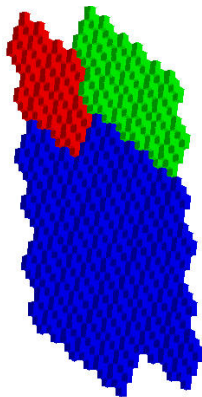


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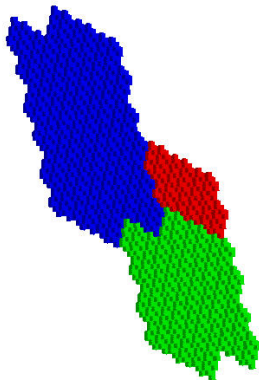


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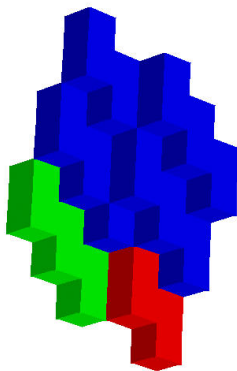
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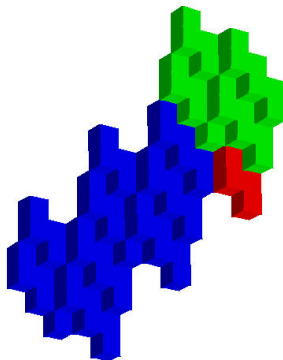
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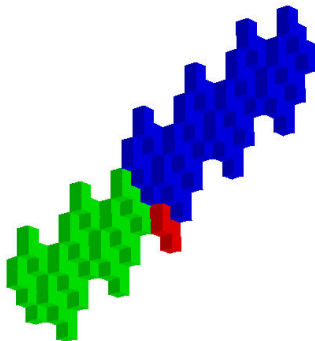
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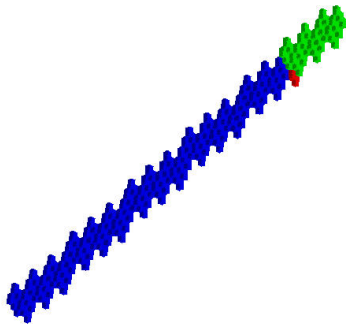
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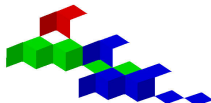


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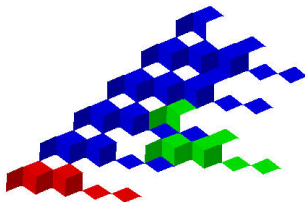


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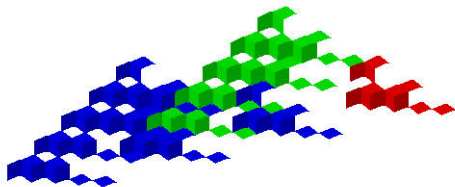


Examples in dimension 3

Starting with the unit cube $\mathcal{U} = (\vec{0}, e_1^*), (\vec{0}, e_2^*), (\vec{0}, e_3^*)$.

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There exists N such that for all $n \geq N$, $\sigma_{\langle n \rangle} = \sigma_{\text{Id}}$.

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For all $n \geq 1$, $\sigma_{\langle n \rangle} = \sigma_{B_n, C_n}$.
 $\implies |\{(\vec{x}, e_i^*) \in \mathcal{T}\}|$ is an infinite *potato*.

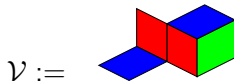
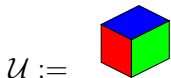
Generating the whole plane $\mathfrak{G}_{\vec{\alpha}}$, with $\dim_{\mathbb{Q}}(a, b, c) = 3$

- ★ There exists $n_0 \geq 1$ such that for all $k \geq 0$
 - $B_{n_0+3k} = C_{n_0+3k}$,
 - $C_{n_0+3k+1} - B_{n_0+3k+1} \geq 1$,
 - $B_{n_0+3k+2} = 0$.

Generating the whole plane $\mathfrak{G}_{\vec{a}}$, with $\dim_{\mathbb{Q}}(a, b, c) = 3$

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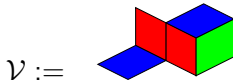
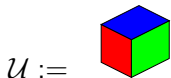
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Theorem (Ito, Ohtsuki)

Given $\dim_{\mathbb{Q}}(a, b, c) = 3$,

If the condition ★ holds then

$$\mathfrak{G}_{(a,b,c)} = \lim_{n \rightarrow \infty} E_1^*(\sigma_{\langle 1 \rangle}) \circ \cdots \circ E_1^*(\sigma_{\langle n \rangle})(\mathcal{V}).$$

Otherwise,

$$\mathfrak{G}_{(a,b,c)} = \lim_{n \rightarrow \infty} E_1^*(\sigma_{\langle 1 \rangle}) \circ \cdots \circ E_1^*(\sigma_{\langle n \rangle})(\mathcal{U}).$$

$$\mathcal{W} = \begin{cases} (\vec{0}, e_3^*) & \text{if } \dim_{\mathbb{Q}}(a, b, c) \leq 2, \\ \mathcal{U} & \text{if } \dim_{\mathbb{Q}}(a, b, c) = 3 \text{ and not } \star, \\ \mathcal{V} & \text{if } \dim_{\mathbb{Q}}(a, b, c) = 3 \text{ and } \star. \end{cases}$$

Theorem (Berthé, Lacasse, Paquin, P.)

For any $n \geq 1$, the pattern $\mathcal{T}_n = E_1^(\sigma_{\langle 1 \rangle}) \circ \cdots \circ E_1^*(\sigma_{\langle n \rangle})(\mathcal{W})$ is a simply connected set.*

Polyamond patterns

Let π_0 be the orthogonal projection on the plane

$$\mathcal{P}_0 : x + y + z = 0.$$

Definition

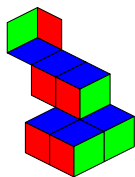
A pattern \mathcal{X} is a *polyamond pattern* if the topological boundary of its projection $\pi_0(\mathcal{X})$ is a Jordan curve.

Polyamond patterns

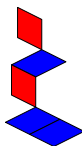
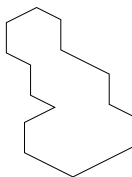
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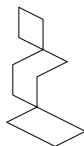
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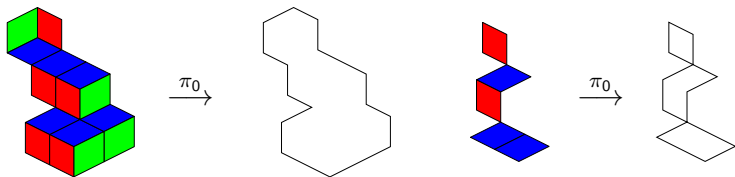


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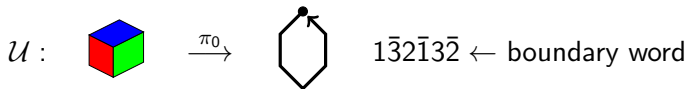


Proposition

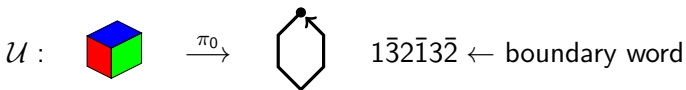
A polyamond pattern \mathcal{X} is simply connected.

Eight-curves

$$\bar{\mathcal{A}}_3 = \{1, 2, 3, \bar{1}, \bar{2}, \bar{3}\}$$



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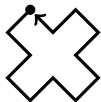


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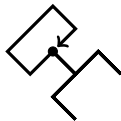
Given a word $w \in \bar{\mathcal{A}}_d^*$

- w is a *closed curve* if $\vec{w} = \vec{0}$ and $\pi_{F_d}(w) \neq \varepsilon_{F_d}$, where π_{F_d} is the canonical projection from $\bar{\mathcal{A}}_d^*$ to the free group F_d .
- w is an *eight-curve* if it is a closed curve and if it admits a conjugate of the form $w \equiv uv$ where u and v are closed curves.

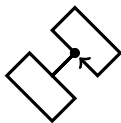
Examples



$$\underbrace{1212\bar{1}2\bar{1}\bar{2}\bar{1}2\bar{1}\bar{2}}_{\bar{0}}$$



$$\underbrace{2\bar{1}2\bar{2}\bar{1}12\bar{2}\bar{1}\bar{2}}_{\bar{0}} \underbrace{1\bar{2}\bar{1}\bar{1}21}_{\bar{0}}$$



$$\underbrace{121\bar{2}\bar{2}\bar{1}2\bar{1}}_{\bar{0}} \underbrace{\bar{2}\bar{1}221\bar{2}}_{\bar{0}}$$



$$\underbrace{\bar{3}1\bar{3}\bar{1}3}_{\bar{0}} 2\bar{1}\bar{2}31$$

Proposition






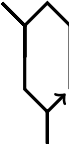
The boundary word of a pattern \mathcal{X} that is not a polyiamond pattern is an eight-curve.

Theorem (Ei)

Let \mathcal{X} be a pattern with boundary word w and σ be a primitive unimodular substitution, then $\widetilde{\sigma^{-1}(w)}$ is a boundary word for $E_1^(\sigma)(\mathcal{X})$.*

Example

Let σ be the Tribonacci substitution : $\sigma(1) = 12$, $\sigma(2) = 13$,

k	$E_1^*(\sigma^k)(\vec{0}, e_1^*)$	$(\widetilde{\sigma^{-1}})^k(23\bar{2}\bar{3})$
0		 $23\bar{2}\bar{3}$
1		 $1\bar{3}2\bar{3}\bar{3}1\bar{3}\bar{2}$
2		 $3\bar{3}\bar{2}1\bar{3}\bar{3}\bar{2}\bar{2}\bar{3}\bar{3}\bar{2}\bar{3}\bar{3}1$

We define some set of forbidden words E such that given any substitution σ obtained by the Jacobi-Perron's algorithm

- For any word w , $\widetilde{\sigma^{-1}(w)} \in E$ implies that $w \in E$.
- Eight-curves are included in E .
- The boundary words of the generating patterns \mathcal{W} are not in E .

Conclusion

Given any vector $\vec{\alpha} = (a, b, c) \in \mathbb{R}^3$, for any $n \geq 1$

$$\mathcal{T}_n = E_1^*(\sigma_{\langle 1 \rangle}) \circ \cdots \circ E_1^*(\sigma_{\langle n \rangle})(\mathcal{W})$$

is a simply connected subset of $\mathfrak{G}_{\vec{\alpha}}$.

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Moreover, let $\mathcal{T} = \lim_{n \rightarrow \infty} \mathcal{T}_n$:

- if $\dim_{\mathbb{Q}}(a, b, c) = 1$ then \mathcal{T} is finite and there exist two vectors $v_1, v_2 \in \mathbb{Z}^3$ that generate a periodic tiling of $\mathfrak{G}_{\vec{\alpha}}$ by \mathcal{T} ,

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- if $\dim_{\mathbb{Q}}(a, b, c) = 2$ then \mathcal{T} is infinite and there exists a vector v that generates a semi-periodic tiling of $\mathfrak{G}_{\vec{\alpha}}$ by \mathcal{T} ,
- if $\dim_{\mathbb{Q}}(a, b, c) = 3$ then $\mathcal{T} = \mathfrak{G}_{\vec{\alpha}}$.

MERCI !